

Mirror Tech Days 2006

BAUER

Integration of Full-Spectrum Metrology and Polishing for Rapid Production of Large Aspheres

Paul Glenn

September 18, 2006

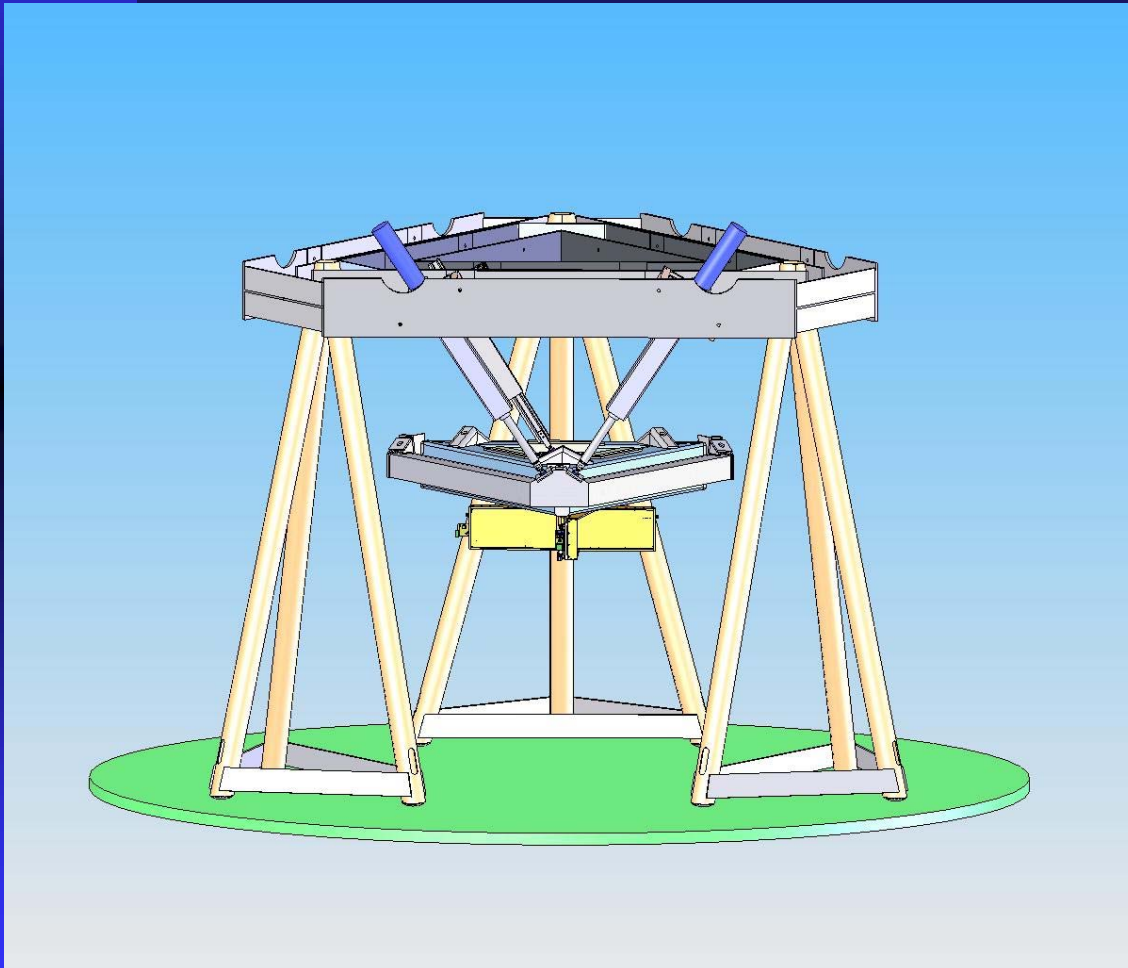
Topics

BAUER

- ◆ Integrated, in situ approach to metrology and polishing
 - ◆ Hexapod system
- ◆ Metrology
 - ◆ Full aperture (low frequency)
 - Overview
 - Demonstration measurements
 - ◆ Mid frequency
 - Overview
 - Demonstration measurements
 - ◆ Micro-roughness (high frequency)
- ◆ Polishing
- ◆ Machine status and schedule

Integrated, in situ approach

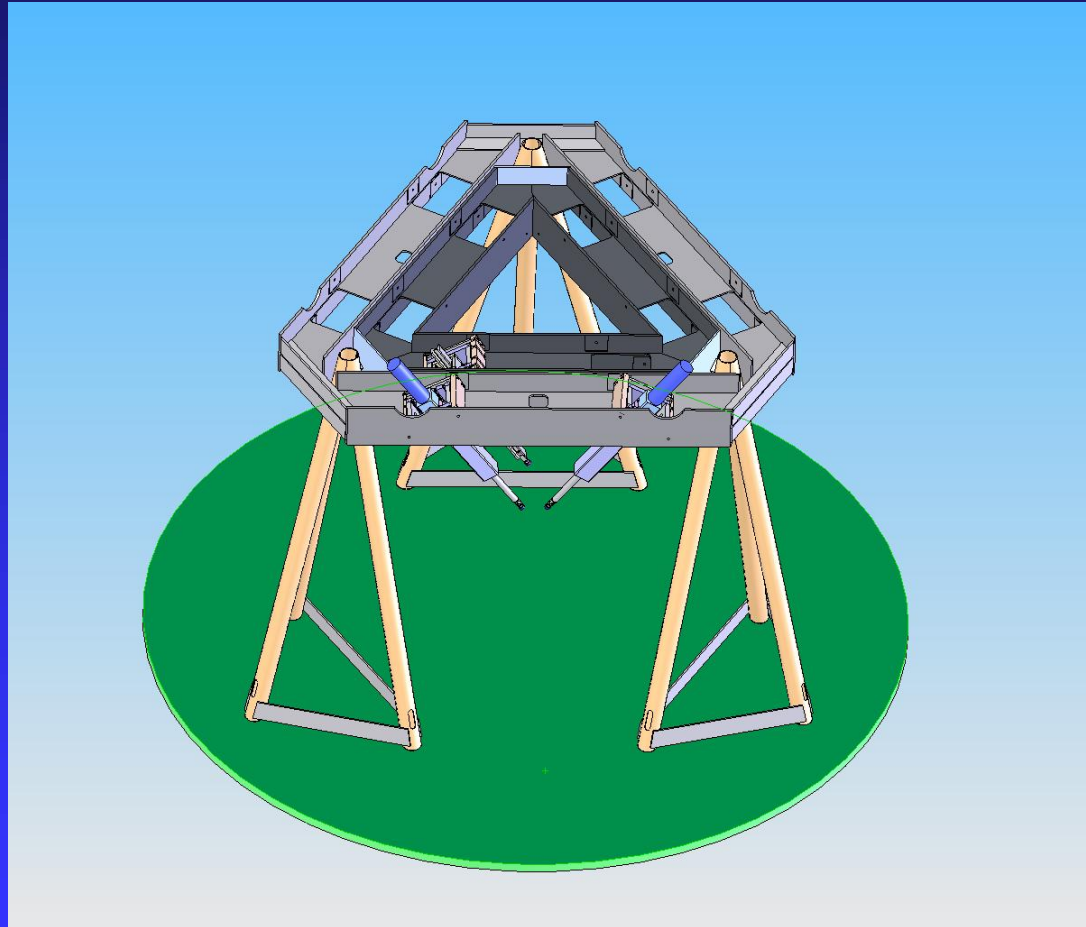
BAUER



- ◆ A hexapod structure moves a “platter” in all degrees of freedom over the substrate
- ◆ The platter integrates all metrology and polishing functions

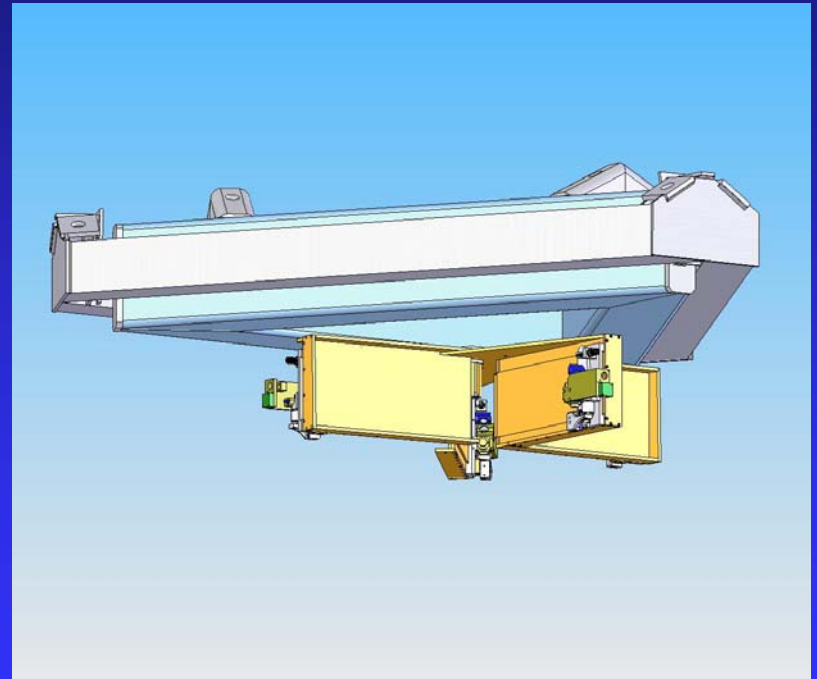
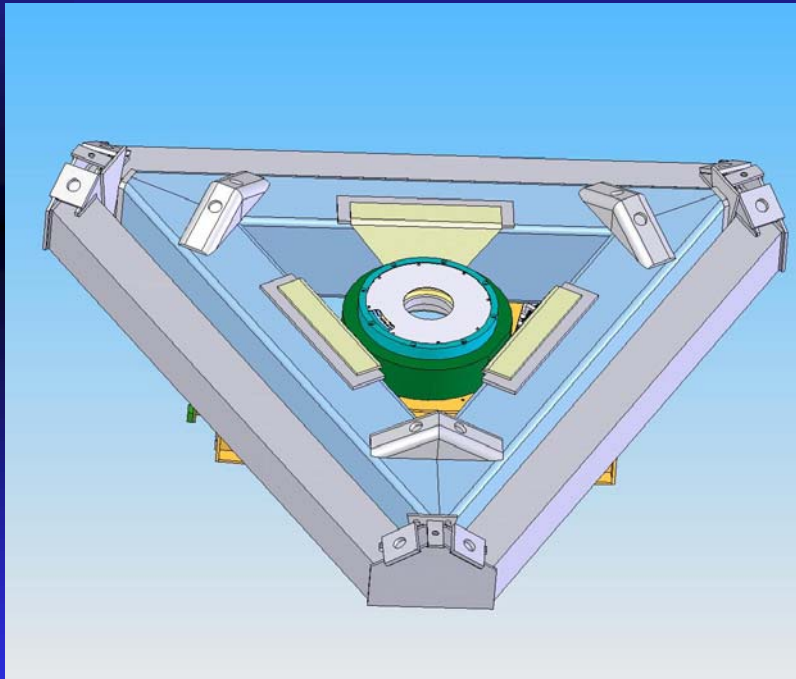
Upper frames for actuation and encoding

BAUER



Lower (“platter”) frames for actuation and encoding

BAUER



Three types of metrology

BAUER

- Full aperture (low frequency)
 - ◆ “4 point” optical profilometer
- Mid frequency
 - ◆ Curvature-based optical profilometer
- Micro-roughness (high frequency)
 - ◆ Total Integrated Scatter (TIS)

“4 point” profilometry (full aperture figure msmnts)

BAUER

- Limitations of interferometry, profilometry
- Three basic principles of 4-point operation
- Summary of advantages
- Demonstration measurements
- Performance predictions

The three basic principles of 4-point profilometry...

BAUER

- If a rotating platter axis intersects the optic center of curvature, then a probe on the platter nominally sees no change in standoff (convex or concave substrate!)
- If four or more probes are on a platter, then there is *some* linear combination of their readings that

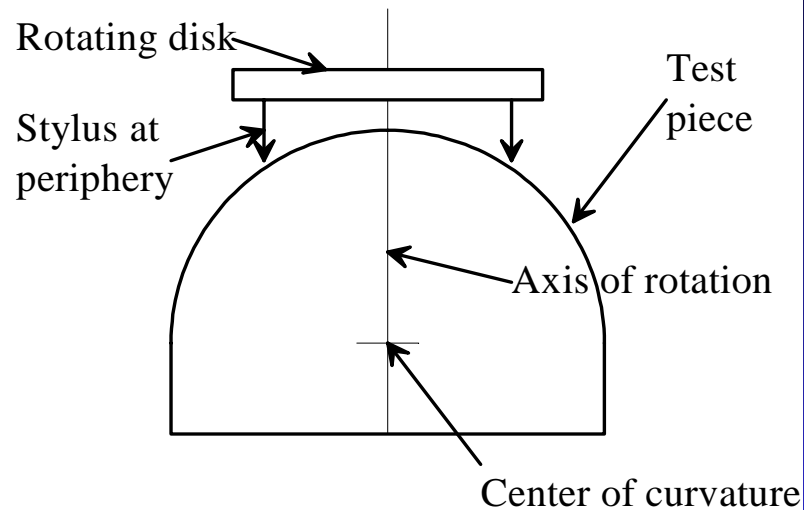
- ◆ (1) is insensitive to all rigid body motions
- ◆ (2) tells *something* about the shape of the test piece

A continuous measurement of this linear combination as the platter rotates yields a circular “hoop” profile

- If one measures multiple “hoops” around a test piece, with each overlapping at least two others, then it is possible to “stitch” the profiles to obtain the total surface height map.

The three principles...

BAUER



Trivial example:

$\text{Sum} = A - B + C - D$

Piston invariant

X-tilt invariant

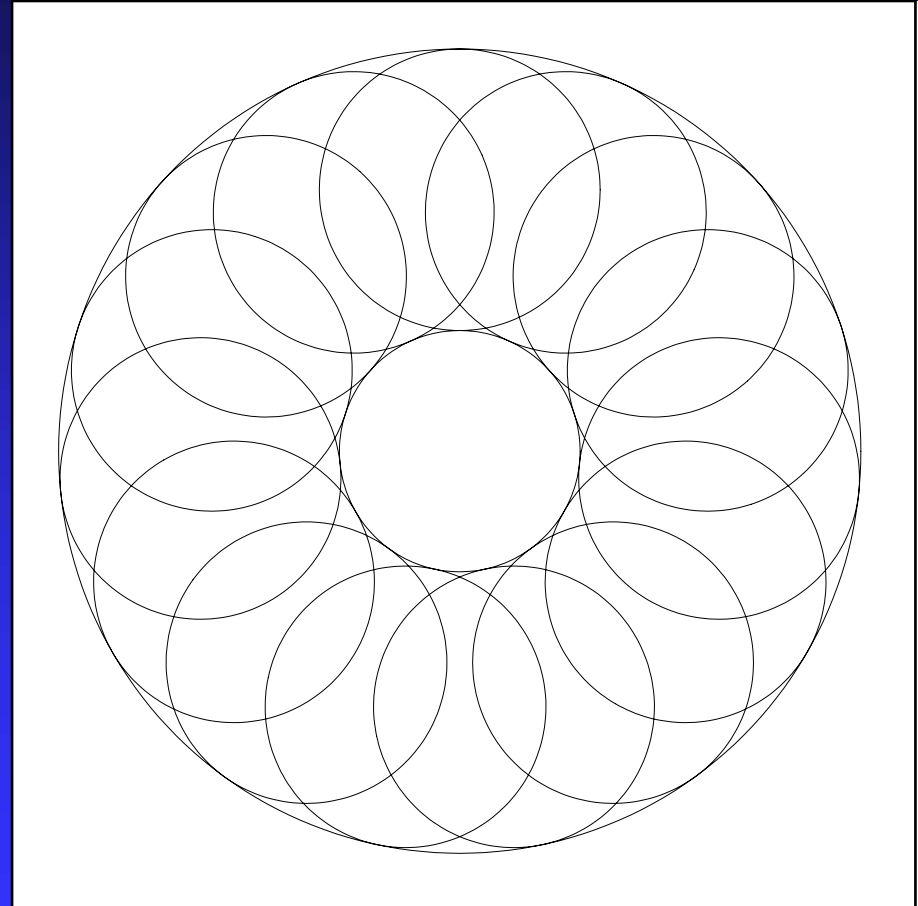
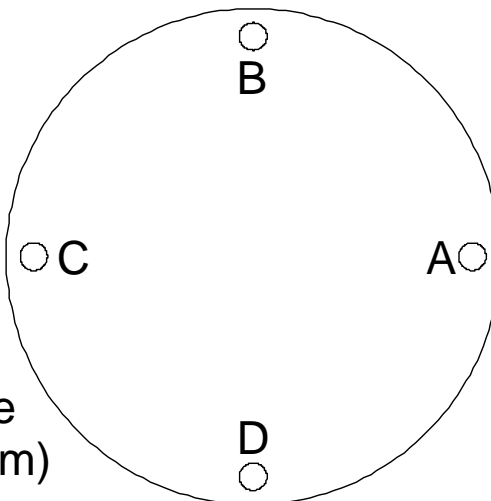
(A incr, C decr)

Y-tilt invariant

(B incr, D decr)

Sees some shape

(e.g., astigmatism)



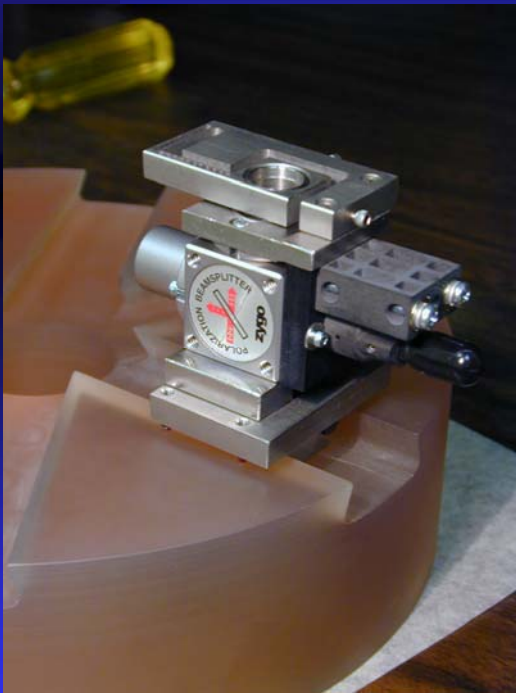
Summary of advantages

BAUER

- Does not work from center of curvature, thus not requiring a massive test tower
- Equally able to test concave and convex optics
- Completely self referencing
- Insensitive to rigid body motions of the test piece during measurements
- (Specially developed laser gauge probes provide absolutely reliable scale factor and mm-class range)
- By replacing the laser gauge probes with coarse probes (touch probes or non-contact alternatives), the instrument can measure optics in their ground state. Thus, one metrology instrument can take an optic from generation through final polish.

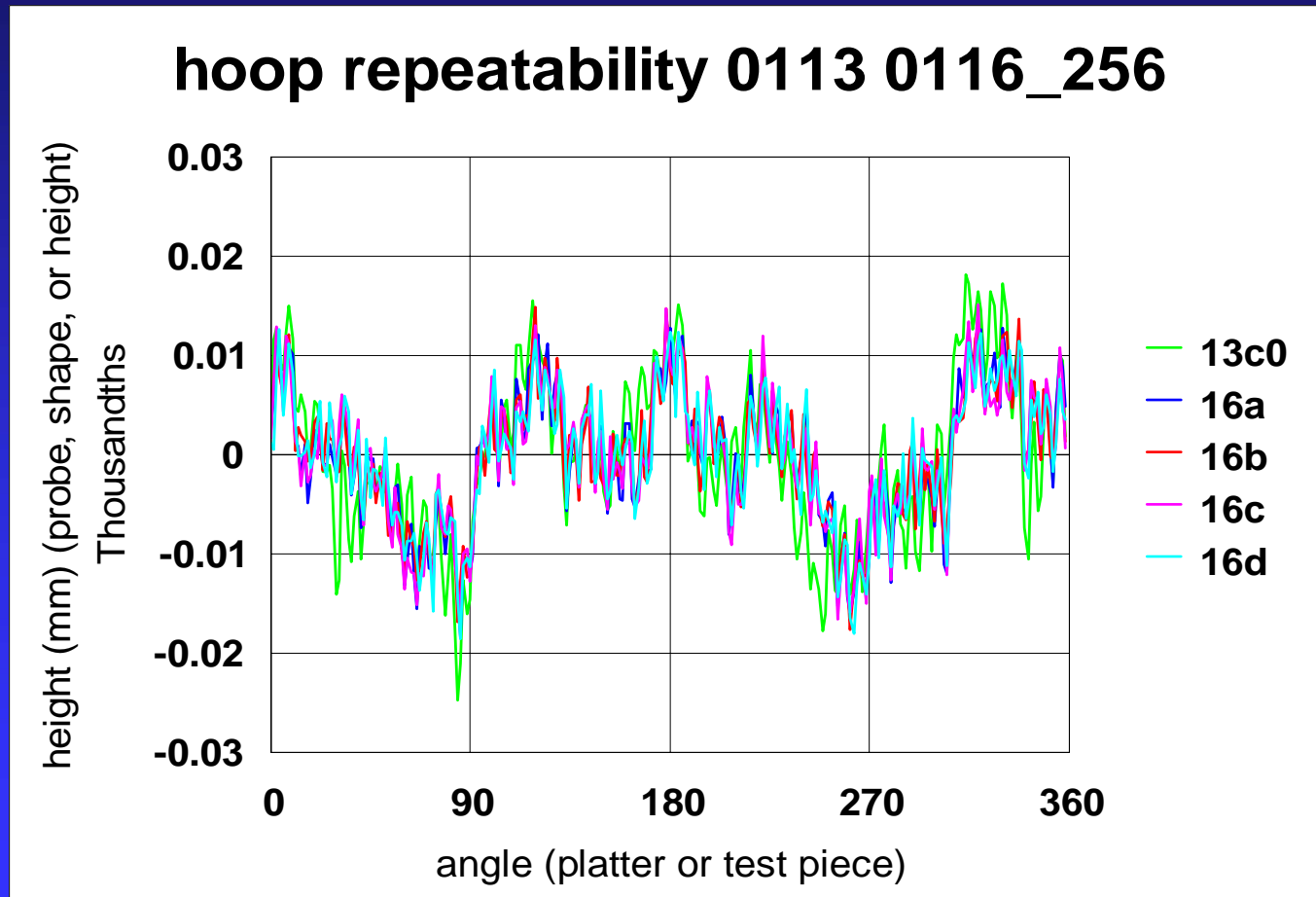
“Platters” – Original, and current for 1.25 m mirrors

BAUER



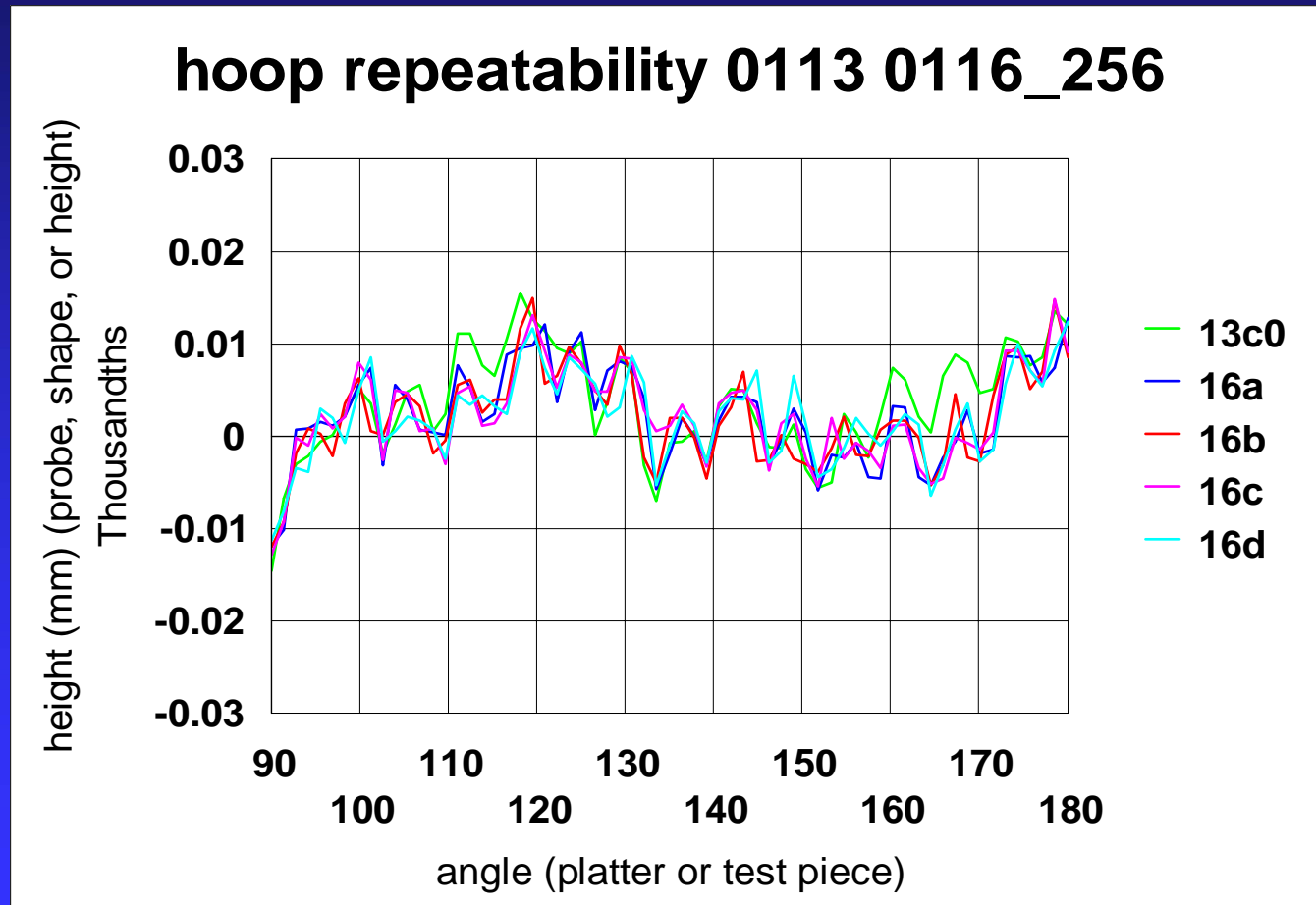
“Hoop” repeatability over full circumference (three days) (each box is 10 nm)

BAUER



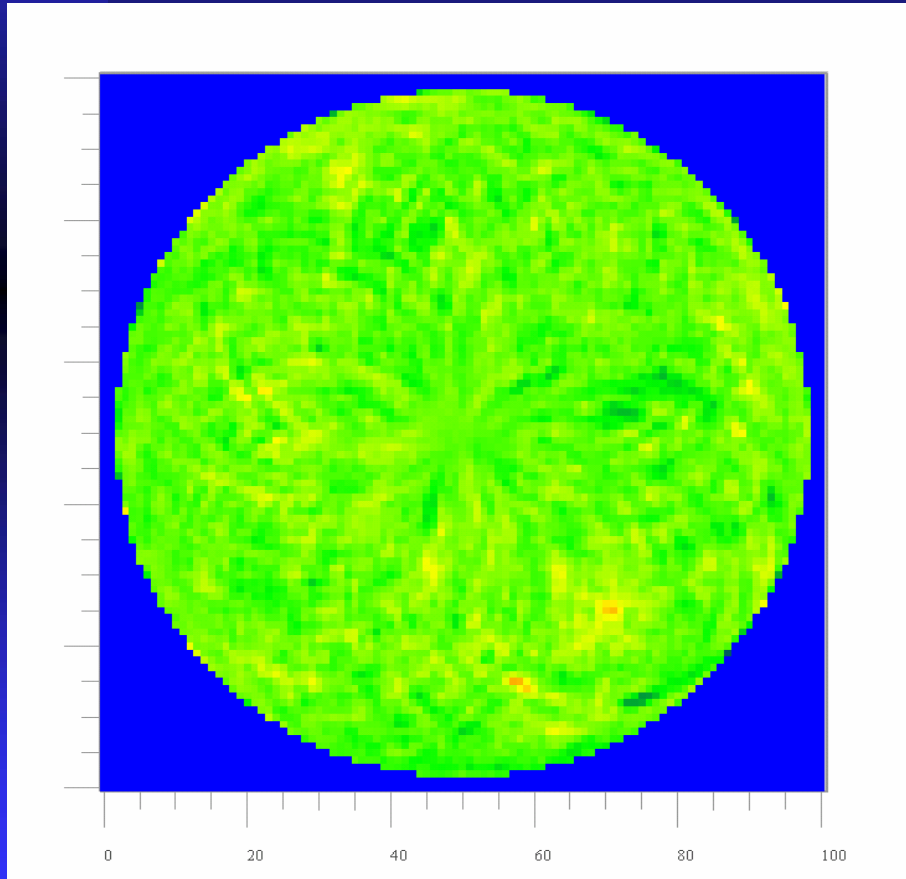
“Hoop” repeatability over just 90 degrees (again, three days) (note 6 mm structure)

BAUER



Full aperture difference between *two independent measurements at different test piece orientations*

BAUER

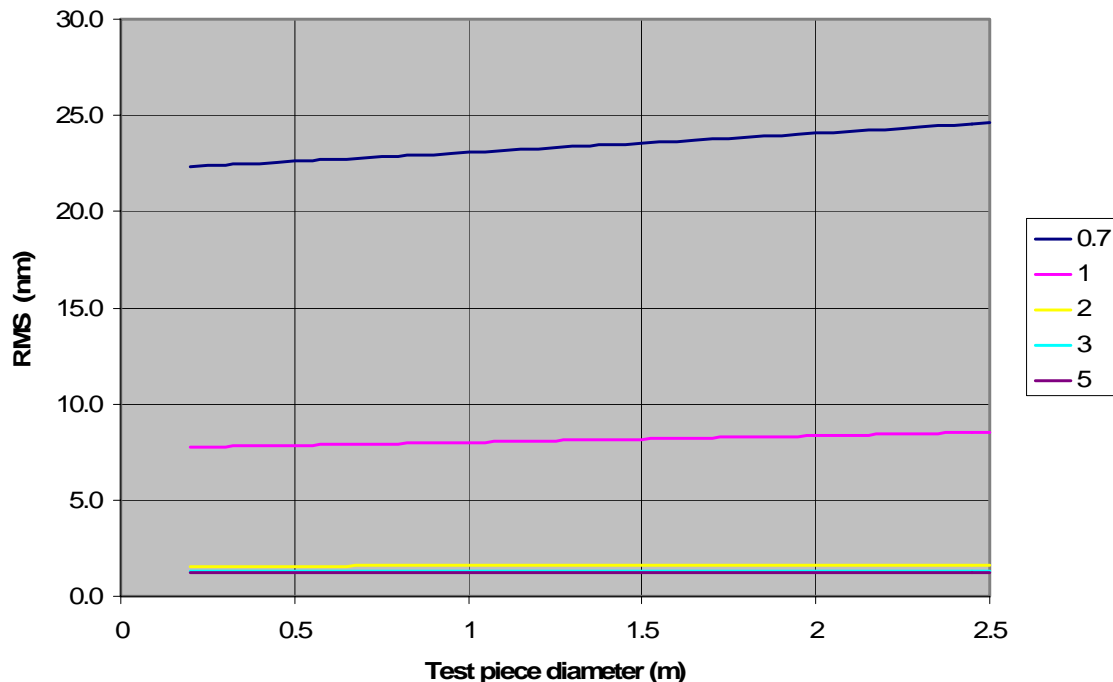


- rms difference = .0025 wave ($\lambda / 402$), or 1.57 nm
- this implies a full aperture error in each measurement of approximately 1.1 nm rms

Predicted ultimate performance

BAUER

Predicted rms figure measurement errors using various parent f#s, $|K|=1$ (parabola), and vertex displ = 0.0 m



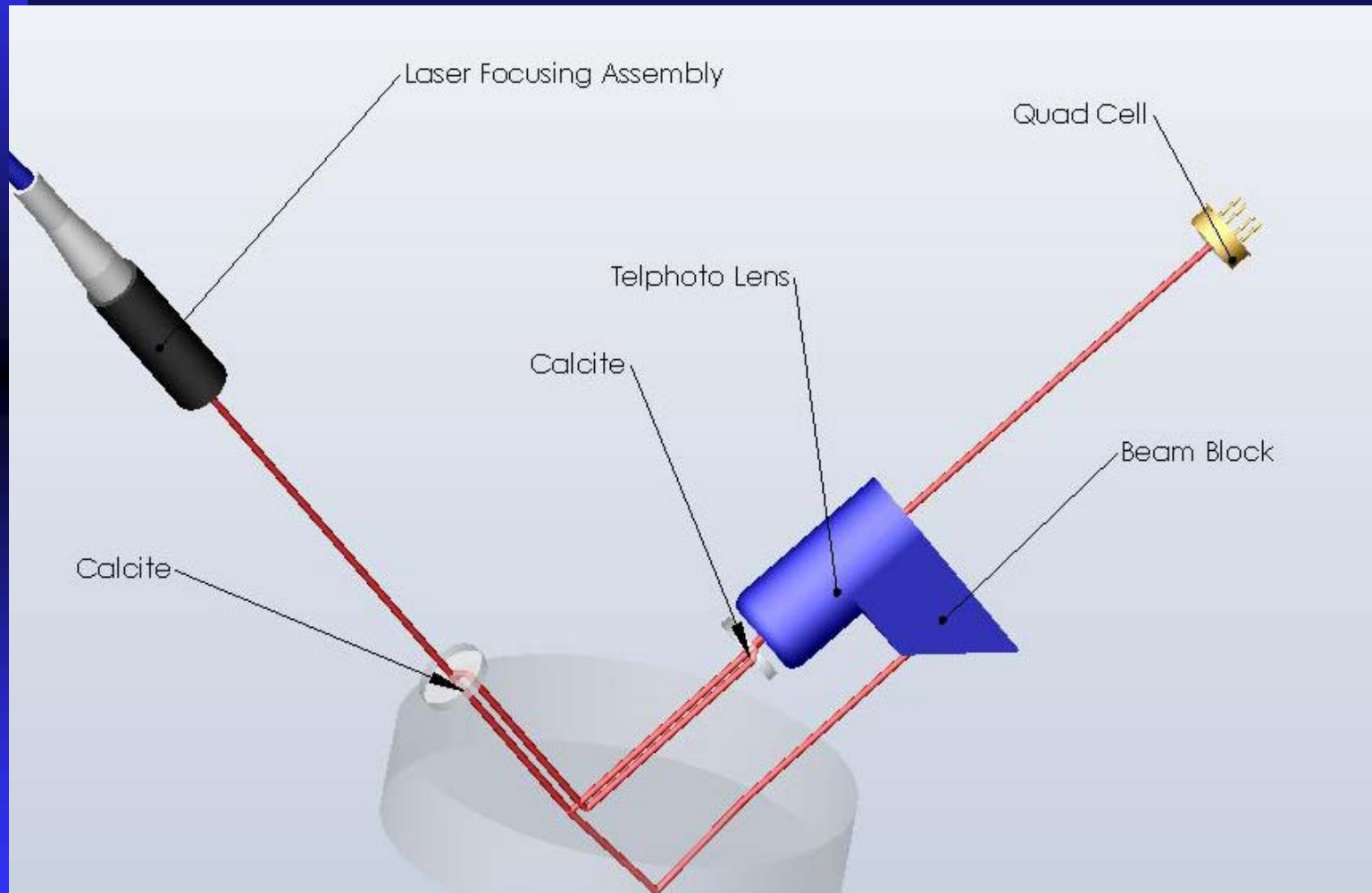
- Assumptions:
 - $K=1$ (parabola)
 - On-axis
- F-numbers examined:
 - F-5 to F-0.7
- Diameters examined:
 - Zero to 2.5 meters
 - (machine under development is 1.25 m)

Mid frequency profilometry **BAUER**

- Optical measurement of curvature profile, based on Bauer's Model 100 Profilometer
- The mid frequency probe is placed on the same "probe circle" as the 4-point profilometer probes
- Each "hoop" profile is thus independently measured in terms of
 - ◆ Low frequency (4-point profilometry)
 - ◆ Mid frequency (curvature-based profilometry)
- The profiles are optimally combined in frequency space based on the (frequency-dependent) error spectra of the two measurements

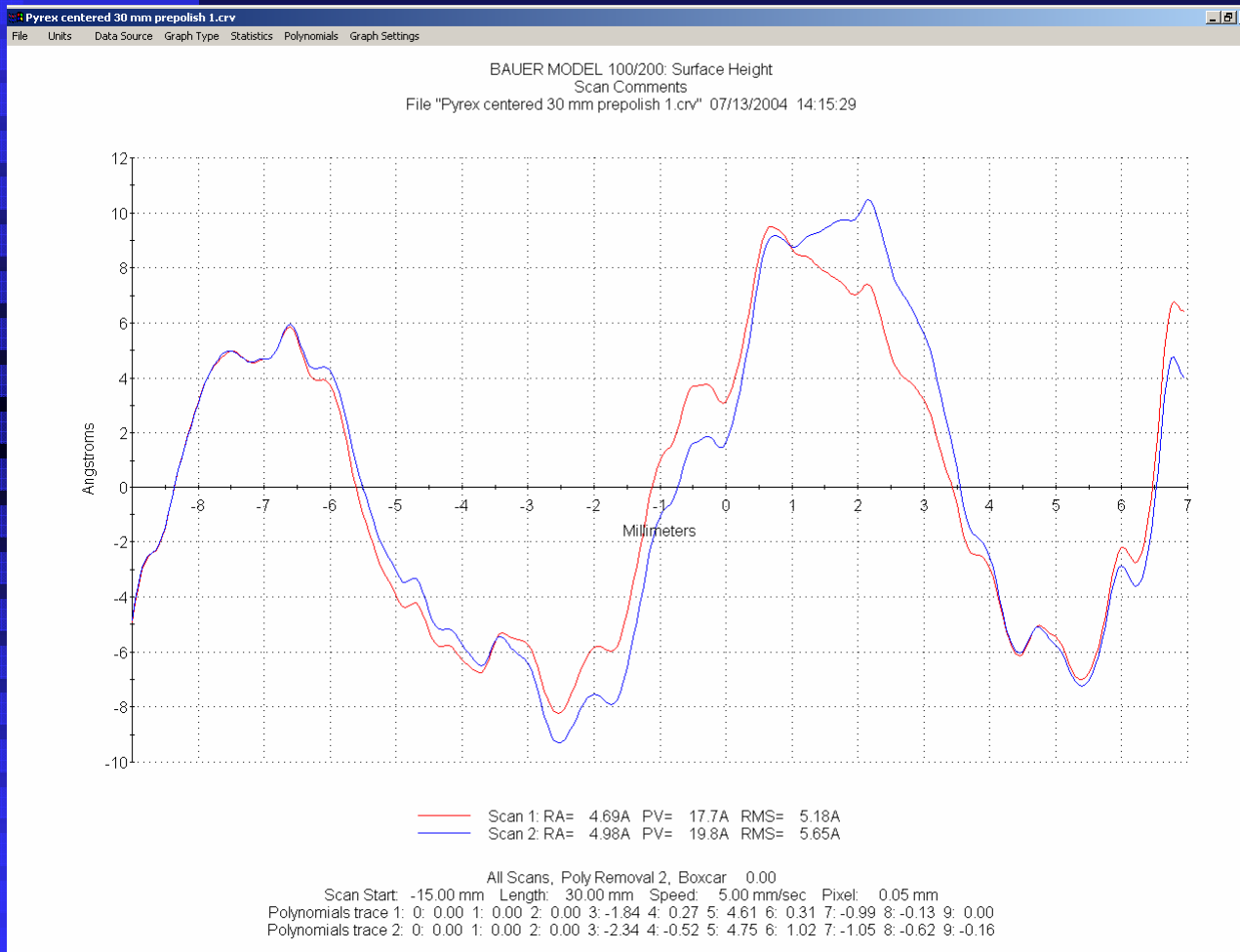
Mid frequency probe

BAUER



Mid frequency data

BAUER



- 15 mm scan is shown
- Each vertical box is 2 Angstroms
- The two scans being compared show rms values of 5.2 and 5.6 Angstroms, with sub-Angstrom rms differences

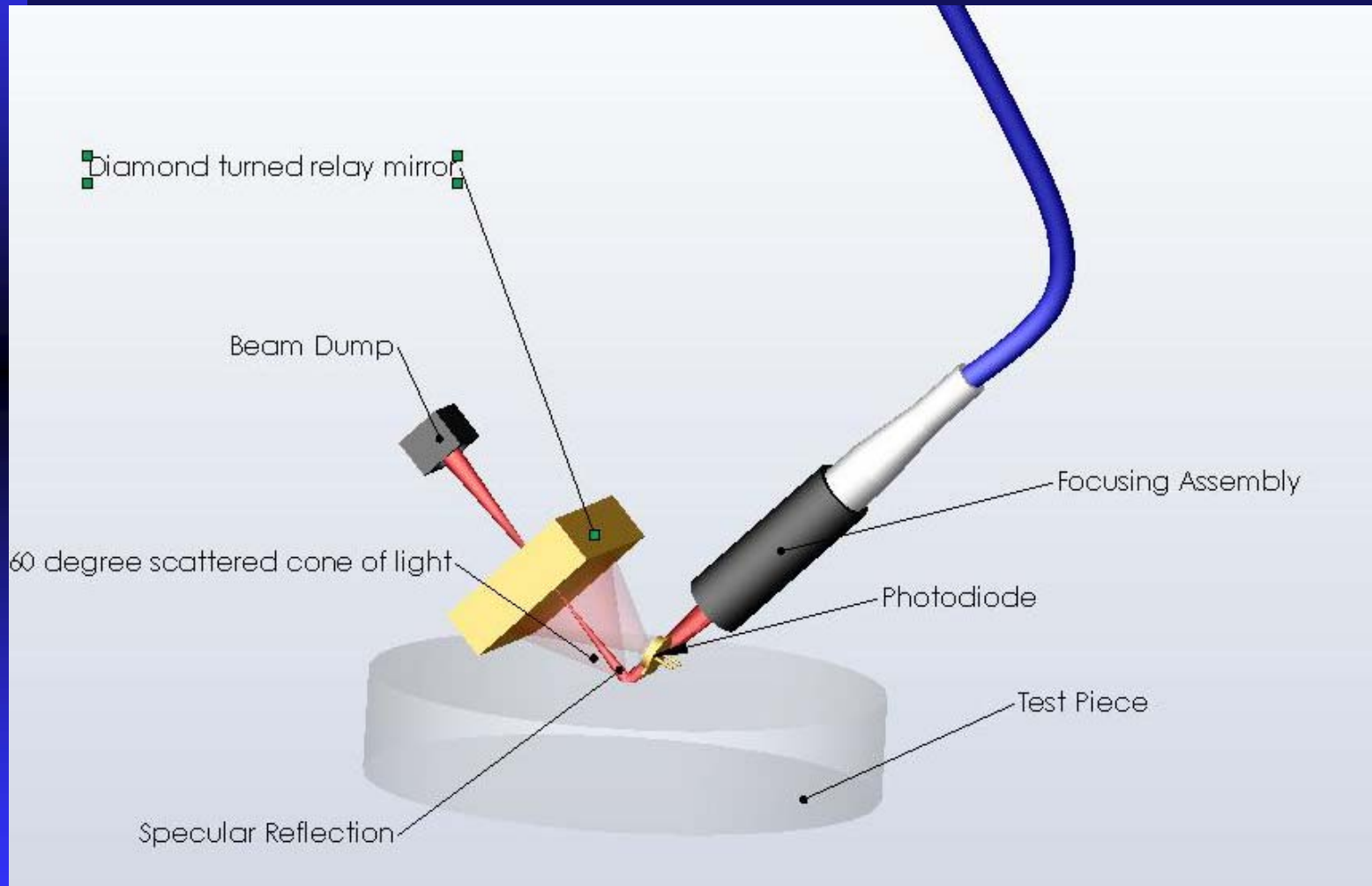
Microroughness

BAUER

- Microroughness is characterized by measuring Total Integrated Scatter (TIS)
- The TIS probe is placed on the same “probe circle” as the 4-point profilometer probes and the mid frequency probe
- TIS is measured, and the band-limited microroughness is calculated and plotted, over the entire surface
- Sensitivity to the 1 Angstrom rms level is expected

TIS probe

BAUER



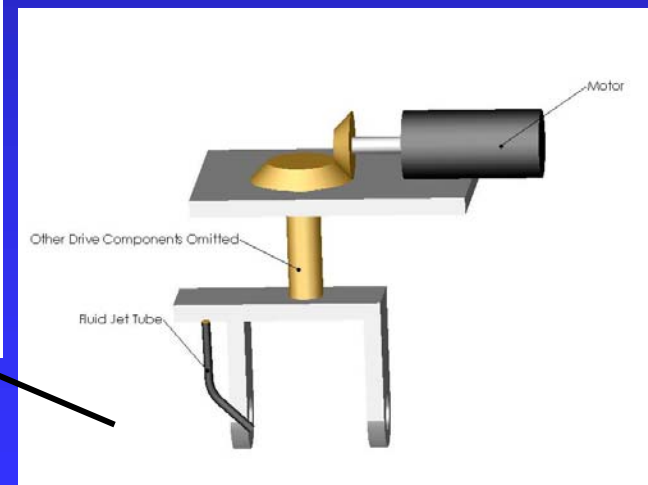
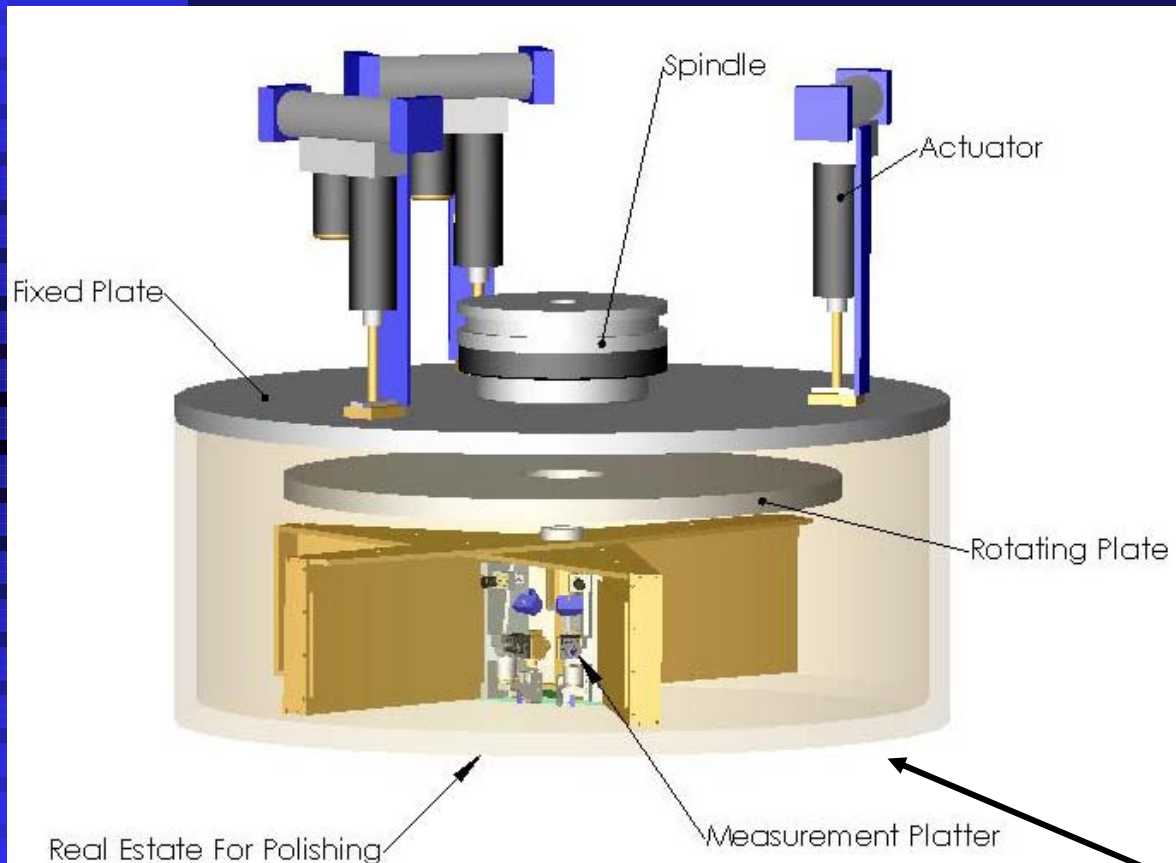
Polishing

BAUER

- Baseline approach is Fluid Jet Polishing (FJP)
- FJP apparatus is incorporated on a bottom “lid” under the platter, thereby using the *same* hexapod infrastructure as the metrology
 - ◆ This is key to our integrated, in situ approach

Polishing

BAUER



Phase I SBIR results for polishing experiments

BAUER

- We used several grit sizes and pump pressures
- We were able to remove hundreds of microns of material with the coarsest grit size and highest pressure
- We found smoothing action to a small fraction of a grit size for a wide range of grit sizes (work in the literature tends to confirm the ability of FJP to polish without degradation of roughness)
- We found excellent preservation of mid frequency figure when polishing for roughness
- Much more polishing work needs to be done at the conclusion of this project, but the prognosis appears good

Status, schedule

BAUER

- We have completed
 - ◆ All of the overall design
 - ◆ Almost all of the detailed structural design
 - ◆ Hexapod calibration algorithms
 - ◆ Much analytical and software work on polishing path generation and dwell optimization (still in process, collaborating with another project)
 - ◆ Performance predictions
 - ◆ Major procurements
- We have begun the machining and assembly

Status, schedule (cont'd)

BAUER

- November '06
 - ◆ Complete superstructure (hexapod) fabrication and initial assembly
- December '06
 - ◆ Achieve first coordinated motions
 - ◆ Integrate the “platter”
- January '07
 - ◆ Get first data from the “4-point” profilometer
- March '07
 - ◆ Fully operational machine